

Abstract

In one embodiment, a vehicular collision avoidance method is provided that includes monitoring a control of a vehicle and activating a first alarm if the control is not adjusted in a sufficient amount of time. The monitored control is normally and regularly adjusted by the vehicle's operator such that the time between adjustments is sufficiently smaller than the time normally needed to avoid a collision after it is detected that the control is no longer being controlled. The first alarm is activated if it is determined that the control is not adjusted in a sufficiently small amount of time from its preceding adjustment. Thus, the vehicle's operator or other vehicle member can react and take measures to ensure that the vehicle is under suitable control upon activation of the alarm and thereby avoid a possible collision.